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## A stylized version of the Aghion-Howitt growth model

Delano S. Villanueva\*

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This short note introduces a compact, self-contained  $3 \times 3$  reduced version of the Aghion-Howitt (AH, Schumpeterian, or creative destruction) model. This stylized reduction aims to capture the three core mechanisms in the AH intuition: (i) innovation (endogenous technological progress), (ii) capital accumulation or production, and (iii) allocation of labor to research & development (R&D) which responds to relative returns. This piece writes the three-equation system, explains every symbol, and outlines the steady-state or balanced-growth conditions as well as the Jacobian for local stability analysis. Developing and emerging economies such as the Philippines, where the R&D sector is actively growing, can benefit from understanding the AH model.

**JEL classification:** E27, O31, O410

**Keywords:** Aghion-Howitt model, endogenous growth, creative destruction, research and development, emerging economies

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### 1. Introduction

After more than three decades, Philippe Aghion and Peter Howitt were awarded the Nobel Prize in Economic Sciences for their model of economic growth through creative destruction. Solow [1956] and Swan [1956] presented the neoclassical growth model with exogenous labor-augmenting technology. Conlisk [1967] modified this model with endogenous technical change, well before Romer [1990], Lucas [1988] and Villanueva [2023; 2021; 2020a; 2020b; 1994; 1971].<sup>1</sup>

This note introduces a compact, self-contained  $3 \times 3$  reduced version of the Aghion-Howitt (AH, Schumpeterian, or creative destruction) model. It is a stylized reduction aimed at capturing the three core mechanisms in the AH intuition: (i) innovation (endogenous technological progress), (ii) capital accumulation or production, and (iii) allocation of labor to research & development (R&D)

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<sup>1</sup> Romer made investments in research and development (R&D) endogenous variables, while Lucas considered investments in education endogenously determined. Villanueva [1971; 2021] incorporated Romer and Lucas in a productivity sector that includes new capital construction and made (i) labor-augmenting technical change endogenous via adopting Arrow's [1962] learning-by-doing [Villanueva 1994; 2020b; and 2023] and (ii) labor participation endogenous via real wage adjustments [Villanueva 2020a].

which responds to relative returns. This short piece writes the three-equation system, explains every symbol, and outlines the steady-state or balanced-growth conditions as well as the Jacobian for local stability analysis. Developing and emerging economies such as the Philippines, where the R&D sector is actively growing, can benefit from understanding the AH model.

## 2. The model

### 2.1. State variables

- $A(t)$ : aggregate technology or “quality” level (scale variable)
- $k(t)$ : capital per worker
- $s(t) \in [0,1]$ : share of labor allocated to R&D (innovation intensity)

### 2.2. Parameters (all positive):

- $\alpha \in (0,1)$ : capital share in production
- $\sigma \in (0,1)$ : saving rate or the fraction of non-R&D output invested
- $\chi > 0$ : productivity of R&D or how effective R&D is in producing technological growth
- $\delta \geq 0$ : depreciation of capital
- $n \geq 0$ : exogenous population and labor growth or dilution rate
- $\beta > 0$ : speed of adjustment of the R&D labor share
- $\kappa > 0$ : parameter compressing the production side return to a comparable unit

The functional form for output per worker is:

$$y(t) = A(t)k(t)^\alpha.$$

### 2.3. Dynamics (reduced system)

#### 2.3.1. Technology (innovation)

$$\dot{A}(t) = \chi s(t)A(t) \tag{1}$$

Innovation increases the technology stock proportionally to current technology and the R&D share  $s$ . This is the simplest multiplicative specification consistent with endogenous (span-of-control style) growth.

#### 2.3.2. Capital per worker

Assume a fraction  $1-s$  of labor produces output and a constant fraction  $\sigma$  of that output is saved (invested). Then investment per worker is  $\sigma(1-s)Ak^\alpha$ . Capital per worker grows net of depreciation and dilution:

$$\dot{k}(t) = \sigma(1 - s(t))A(t)k(t)^\alpha - (\delta + n)k(t). \quad (2)$$

### 2.3.3. R&D labor share (selection/return adjustment)

It is assumed that  $s$  responds to the relative expected return to R&D versus production. In reduced form, a logistic or replicator adjustment captures this:

$$\dot{s}(t) = \beta s(t)(1 - s(t))(\chi - \kappa k(t)^{\alpha-1}). \quad (3)$$

### 2.4. Interpretation

- $\chi$  is the marginal return to R&D (per unit of  $s$ , expressed in the same units as the production return)
- $\kappa k(t)^{\alpha-1}$  is a reduced-form marginal return to allocating labor to production (marginal product of labor in production scaled into the same units). If  $\chi$  exceeds that production return,  $s$  tends to rise; otherwise, it tends to fall. The logistic pre-factor  $s(1 - s)$  pins  $s$  to the  $[0,1]$  interval and provides diminishing adjustment when  $s$  is near 0 or 1. As this is a convenient, standard, and reduced form, one can replace this with any other plausible adjustment rule.

## 3. Comments on the structure

- Equation 1 is the canonical multiplicative specification of AH style growth: growth in technology is driven by the intensity of R&D and is proportional to the current level.
- Equation 2 is standard capital accumulation with the twist that only the non-R&D fraction produces output.
- Equation 3 encodes profit or return incentives that move labor into or out of R&D. The specific form is a reduced form. A micro foundation would compute expected profits from R&D versus from production and derive a best-response  $s$  (or an Euler condition).

## 4. Balanced growth and steady states

Because  $A$  multiplies many terms, the model typically does not have a finite stationary  $A^*$  unless  $s^* = 0$ . Instead, we look for a balanced growth path (BGP) where  $A$  and  $k$  grow at the same constant rate  $g$  and  $s$  converges to a constant  $s^*$ . From (1):

$$\dot{A}/A = g = \chi s^*. \quad (4)$$

If  $k$  grows at the same rate  $g$ , then  $\dot{k}/k = g$ . From (2), dividing by  $k$ :

$$g = \sigma(1 - s^*)Ak^{\alpha-1} - (\delta + n).$$

However, on a BGP the level,  $Ak^{\alpha-1}$  must be constant. Solve for  $k^{\alpha-1}$  using (2), set  $\dot{k}/k = g$ :

$$g + (\delta + n) = \sigma(1 - s^*)Ak^{\alpha-1} \rightarrow k^{\alpha-1} = \frac{g + (\delta + n)}{\sigma(1 - s^*)A}. \quad (5)$$

From (3), at an interior steady share  $s^* \in (0, 1)$ ,

$$0 = \chi - \kappa k^{\alpha-1} \rightarrow k^{\alpha-1} = \chi/\kappa. \quad (6)$$

Combine (5) and (6) to eliminate  $k^{\alpha-1}$ :

$$\frac{\chi}{\kappa} = \frac{g + (\delta + n)}{\sigma(1 - s^*)A}.$$

Use (4)  $g = \chi s^*$  to substitute:

$$\frac{\chi}{\kappa} = \frac{\chi s^* + (\delta + n)}{\sigma(1 - s^*)A}.$$

Solve for the ratio  $A(1 - s^*)$  (or for  $s^*$  if desired). Rearranging gives one scalar relation between  $A$  and  $s^*$ ; to get numerical  $s^*$ , normalise one scale (e.g., set  $A = 1$  at one date or solve from microfoundations). The important message: interior  $s^*$  exists where marginal returns equalise (Eq. 6), and growth rate is  $g = \chi s^*$ .

Special corner solutions:  $s^* = 0$  gives zero long-run innovation (then  $A$  constant) and the model reduces to Solow-style capital dynamics;  $s^* = 1$  is extreme full R&D and production collapses. In the AH model,  $0 < s^* < 1$ .

## 5. Linearization/Jacobian (for local stability)

Write the vector  $X = (A, k, s)$ . The Jacobian  $J$  evaluated at a generic point  $A, k, s$  (compute partial derivatives of RHS of Equations 1 to 3):

$$J = \begin{bmatrix} \chi s & 0 & \chi A \\ \sigma(1 - s) \alpha A k^{\alpha-1} & \sigma(1 - s) A \alpha k^{\alpha-1} - (\delta + n) & -\sigma A k^{\alpha} \\ 0 & -\beta s(1 - s) \kappa (\alpha - 1) k^{\alpha-2} & \beta(1 - 2s)(\chi - \kappa k^{\alpha-1}) \end{bmatrix}$$

Given reasonable values of the elements of  $J$ , all eigenvalues of  $J$  have negative real parts so that equilibrium is locally asymptotically stable.

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